



# PPP with Ambiguity Resolution (AR) using RTCM-SSR

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## Abstract

The RTCM SC104 is developing a standard format to disseminate GNSS state space information. The RTCM-SSR (State Space Representation) format will support a variety of applications at different accuracy levels. Different SSR messages are evolved in basically three stages.

Stage 1 enables code-based PPP applications and consists of messages to transport satellite orbit corrections, satellite clock corrections and satellite signal code biases.

The next milestone (stage 2) is approaching standardization and consists of messages for vertical ionospheric total electron contents (VTEC) to enable single frequency code based PPP as well as messages for satellite signal phase biases to enable phase based PPP and ambiguity resolution.

Stage 3 shall concentrate on the development of slant ionospheric total electron content messages (STEC) as well as tropospheric delay messages to allow PPP-RTK, i.e. centimeter accuracy through ambiguity resolution within seconds of observation time.

The presentation discusses the overall RTCM-SSR concepts and development strategies as well as the current status and schedule.

Special focus will be on the consistency of SSR parameters and processing with respect to satellite signal code and phase biases and its relation to ambiguity resolution.



- RTCM SC104 SSR Working Group
- Strategy / Concepts for RTCM-SSR Development
- Satellite Code and Phase Biases
- Carrier Phase Ambiguity Resolution
- RTCM SSR Working Group - Status
- Summary/Outlook



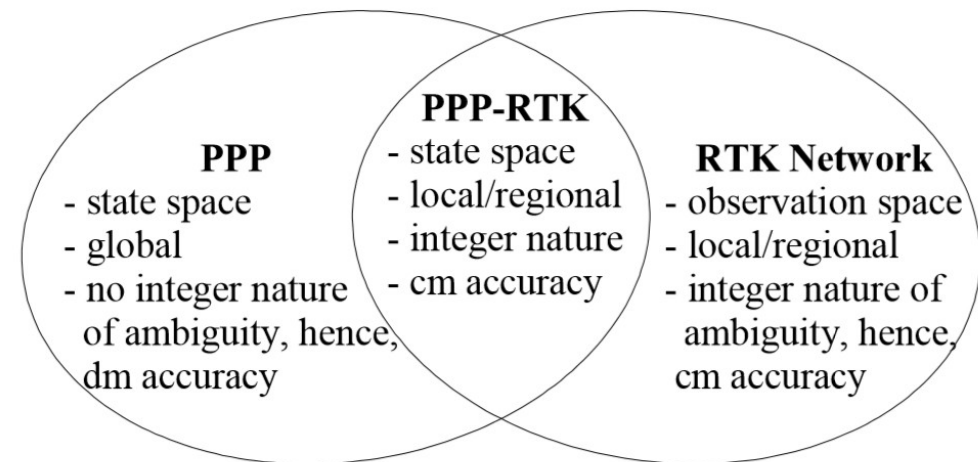
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# RTCM SC104 – SSR Working Group



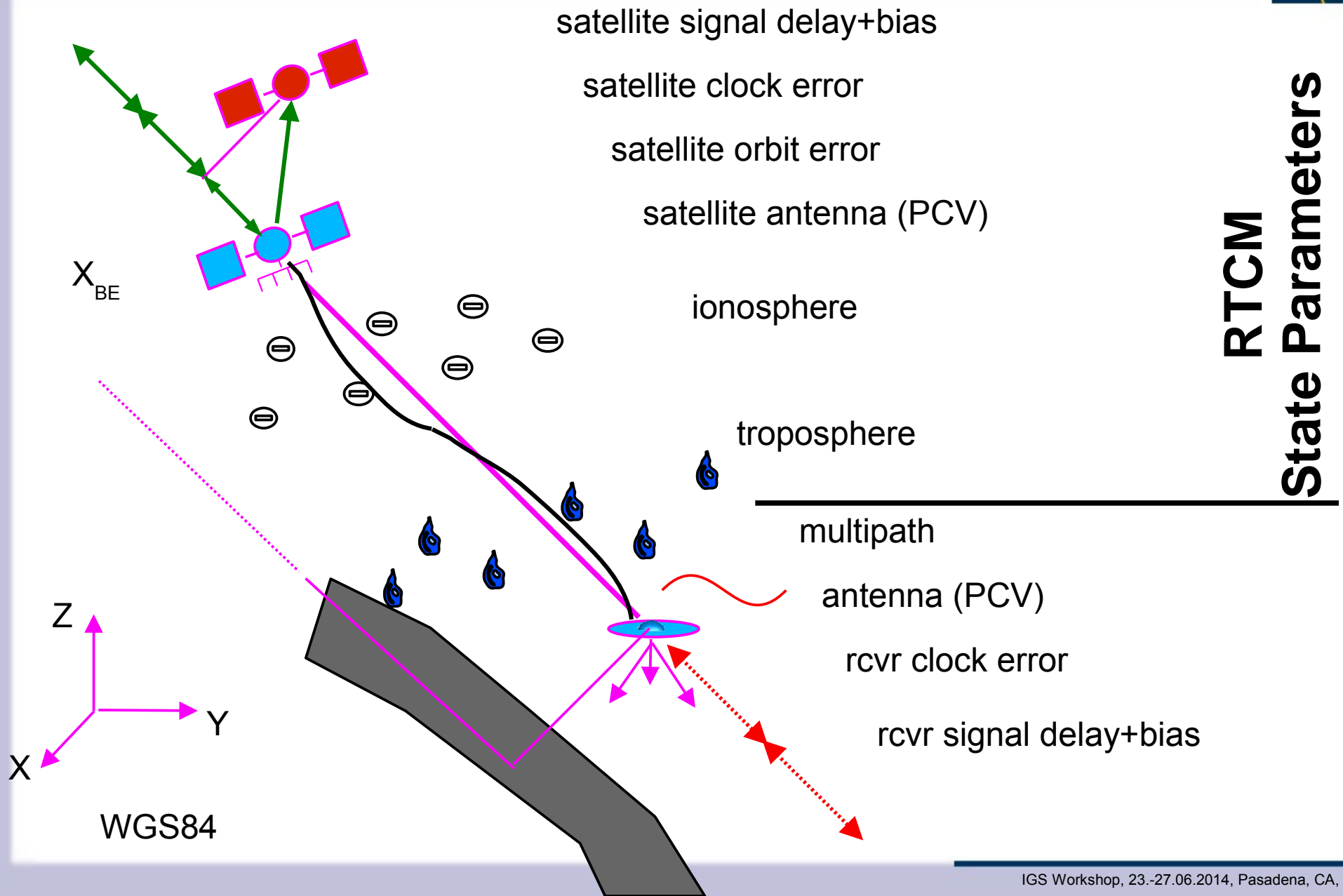
- RTCM SC104 – SSR Working Group established in 2007
  - about 10+ active members
  - about 30+ members in total
- **primary goal**
  - development of RTCM-SSR messages to exchange information about **GNSS error states** (SSR State Space Representation) up to **precise positioning** applications **including RTK**

## Synthesis of PPP and RTK Networking\*



\*Wübbena et.al (2005). PPP-RTK: Precise Point Positioning Using State-Space Representation in RTK Networks. ION GNSS 2005, September 13-16, Long Beach, California.

# Major GNSS Error Sources & RTCM State Parameters





proposed work plan consists of development of RTCM-SSR Messages in **three major stages/steps**:

- Stage 1  
satellite *orbit*, satellite *clock* and satellite *code bias* messages  
to enable **code-based real-time PPP for dual frequency** receivers:  
DF-RT-PPP
- Stage 2  
vertical TEC (*VTEC*) ionospheric message  
to enable **code-based RT-PPP for single frequency** receivers:  
SF-RT-PPP,  
satellite *phase bias* messages  
to enable **phase-based RT-PPP**.
- Stage 3  
ionospheric slant TEC (*STECH*) and *tropospheric* messages  
to enable **RTK-PPP**.



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# Strategy / Concepts for RTCM-SSR Development



- RTCM-SSR shall be a **self-contained** format as far as possible
  - i.e. all necessary information for consistent processing shall be contained in the RTCM-SSR stream or shall be specified in the standard document; the need for external information should be avoided
    - counter example: satellite PCV (tbd)
- the definition of RTCM-SSR contents **shall not limit/restrict** the generation of SSR streams; **no use of particular generation models or approaches**
  - example: conventional approaches with dynamic orbit modeling (IGS) as well as approaches with kinematic orbit modeling shall be supported
- **international conventions for observation modeling and/or corrections** shall be applied **as far as necessary** and as long as they are well defined and documented and freely usable
  - example: IERS convention
- do not prevent new ideas, models or approaches!



- the standard shall allow in a flexible way  
**different update rates for different state parameters**

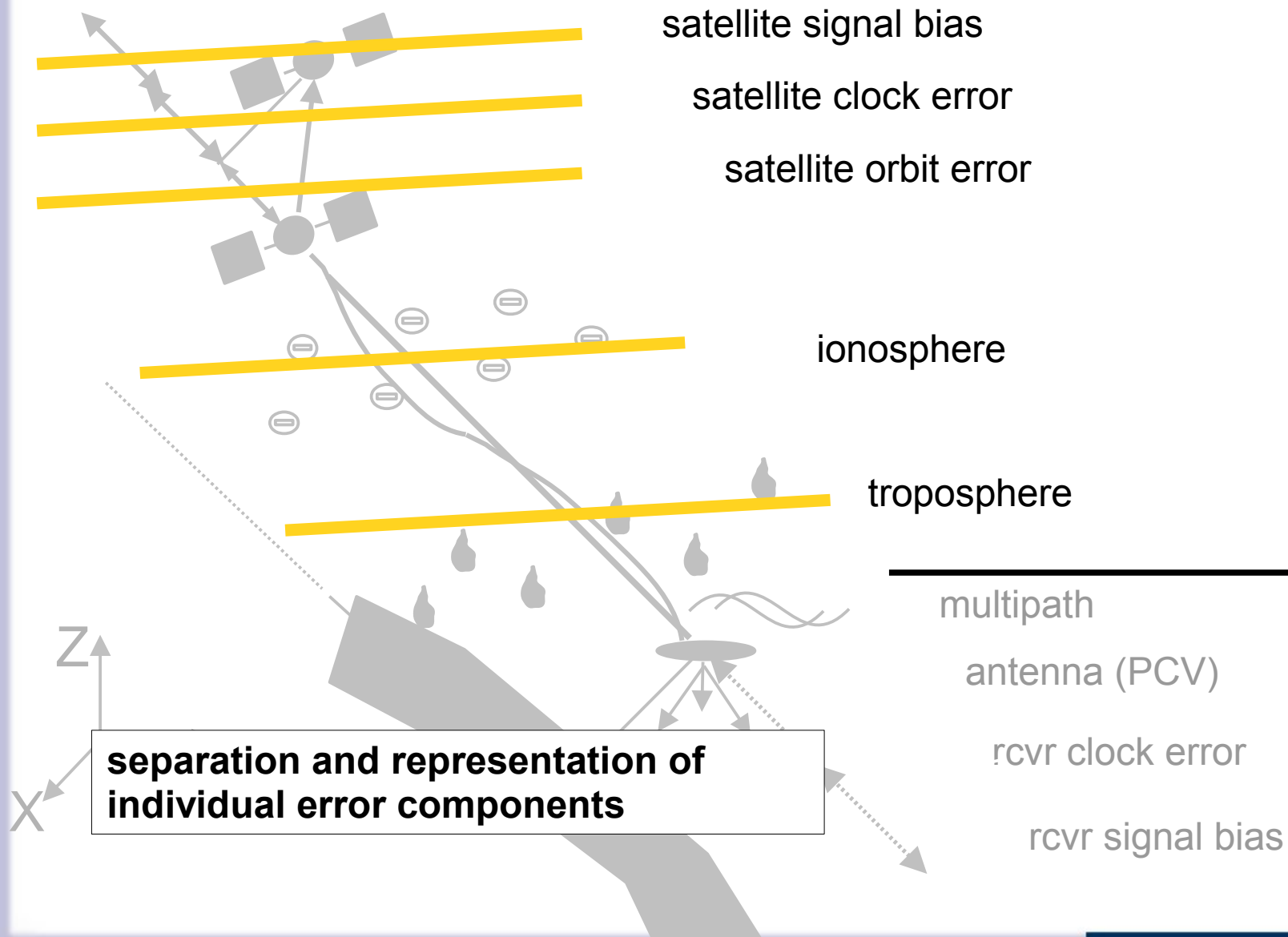
Different error states possess different variability with time. Slowly changing states need lower update rates as highly variable states. This is the key characteristic that allows minimization of stream bandwidth.

- **self-consistency** of RTSM-SSR streams must be achieved
- **consistent processing** of SSR stream contents must be ensured

Consistency is one of the major requirements in order to achieve the desired performance. Consistency of algorithms and computations for reference models must be assured as well as consistency of state parameter sets.

- the RTCM-SSR standard shall support  
**scalable global, continental, regional and/or local applications**

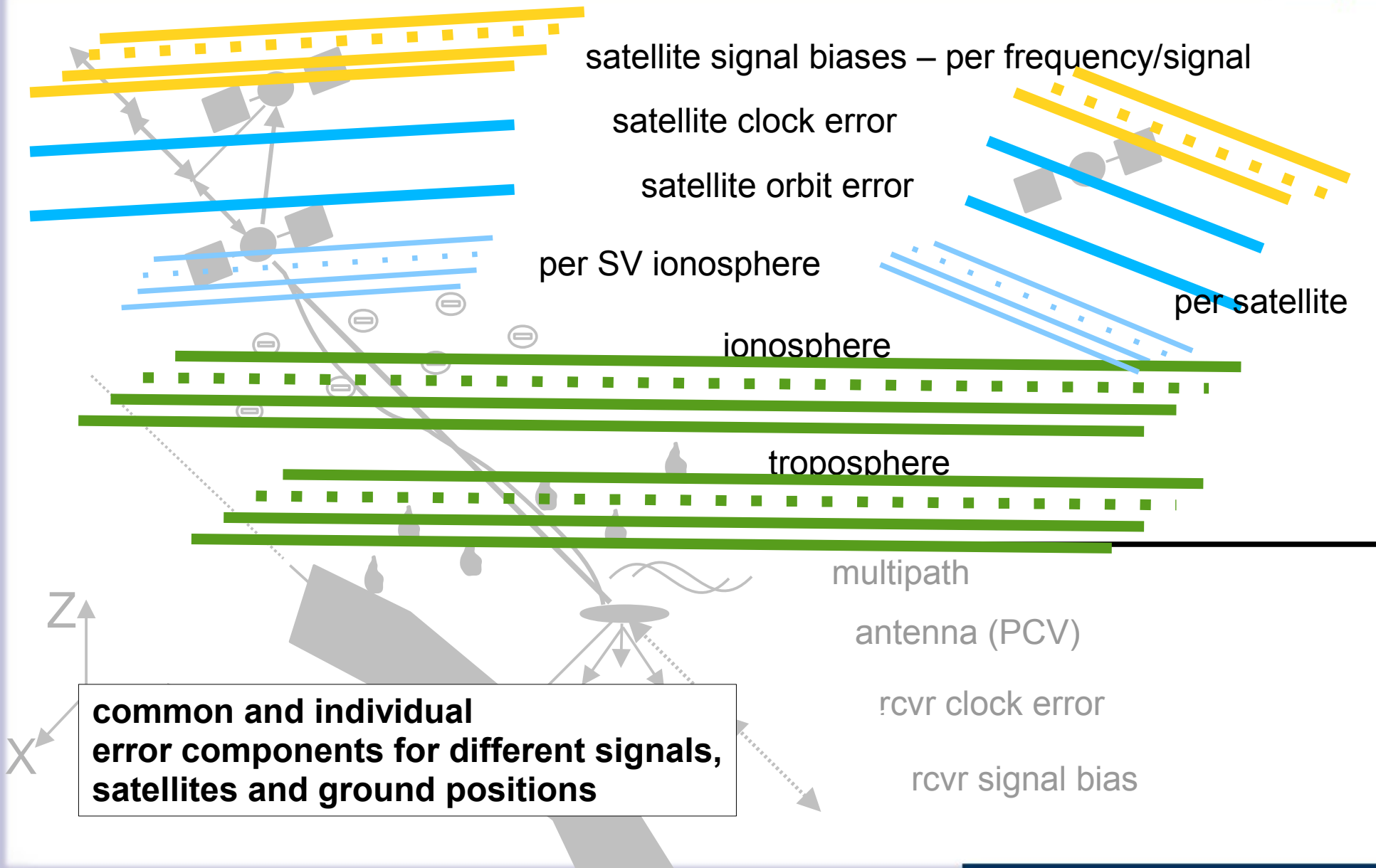
# State Space Representation – GNSS Error States





- **multiple stage models**
  - different messages for same state constituent
  - different **messages are added**
  - added messages add accuracy
  - required for RTCM-SSR development (e.g. spatial variation of atmospheric parameters)
  - **allows for different applications/accuracies**
- **examples**
  - satellite clock
    - initial component clock polynomial
    - optional component high rate clock
  - ionosphere
    - initial model Vertical TEC spherical harmonics
    - additional component slant TEC

# SSR – Spatial Variations of GNSS Atmospheric States





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# Satellite Code and Phase Biases



- **every transmitted GNSS signal** component experiences **a specific signal delay** (bias) in satellite HW/SW
- applies to satellite **code and phase signals**
- example:
  - GPS dual frequency observations:  
**code (P1, P2) and carrier (L1, L2)**
  - error components:  
**satellite clock error dt** and  
**code biases BP<sub>i</sub>** and **phase biases BL<sub>i</sub>**
  - combined clock and signal signal delay error at satellite antenna:

$$\begin{aligned}dP1 &= dt + BP1 \\dP2 &= dt + BP2 \\dL1 &= dt + BL1 \\dL2 &= dt + BL2\end{aligned}$$

linear dependency between clock and bias terms  
==> **only 4 (n\_signal -1) independent parameters**

# Satellite Code and Phase Biases



- **no specific reference bias/signal used** in RTCM-SSR, which allows **maximum flexibility** for service providers
- example
  - complete support of **reference bias/signal** like ionospheric free linear combination of P1, P2 (**GPS/IGS**)
  - **BR** defined to be bias-free gives biased clock and “differential” signal biases:

$$\begin{aligned}dP1 &= (dt + BR) + (BP1-BR) \\dP2 &= (dt + BR) + (BP2-BR) \\dL1 &= (dt + BR) + (BL1-BR) \\dL2 &= (dt + BR) + (BL2-BR)\end{aligned}$$

or

$$\begin{aligned}dP1 &= dt' + BP1' \\dP2 &= dt' + BP2' \\dL1 &= dt' + BL1' \\dL2 &= dt' + BL2'\end{aligned}$$

- **individual signal component (code or carrier)** can be utilized, if corresponding and **consistent bias** is transmitted





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# Ambiguity Resolution



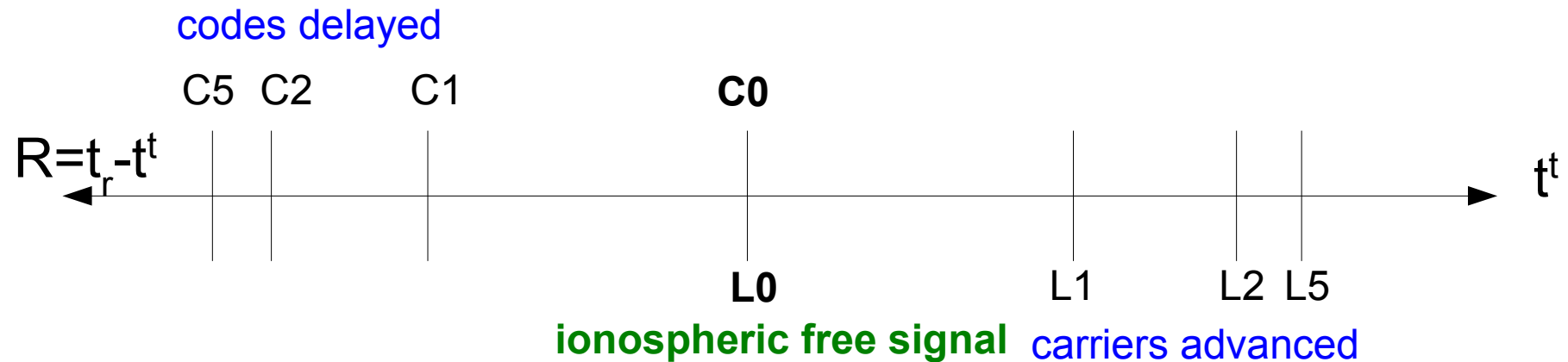
- **RTK** (“centimeters in seconds”) **requires resolution of carrier phase ambiguities**
- different techniques have been developed in the past
  - **GFAR** – **G**eometry **F**ree **A**R
    - linear combinations of different code and carrier signals are used to determine ambiguities
    - often used: **Melbourne-Wübbena - MW**
      - combines carrier wide lane and code “narrow lane” to resolve wide lane ambiguity
  - **GBAR** – **G**eometry **B**ased **A**R
    - utilizes redundant satellites to find the optimal integer ambiguity vector
    - often used: **Lambda** method (Teunissen (1993) Technical University of Delft)
  - **combinations of GFAR and GBAR**

# First Order Ionospheric Effect on Signal Components



- signal components received at the same time have different „apparent“ transmission times
  - higher order ionospheric and multipath effects ignored
  - **satellite code and phase biases are important**

## apparent GPS Signal transmission times (first order iono effect):



- C1, C2, C5 – code epochs on L1, L2, L5 carrier
- L1, L2, L5 – carrier phase epochs
- C0, L0 – ionospheric free (first order) linear combination for code (C0) and carrier (L0)
- **RTK requires ambiguity free L0 or elimination of ionospheric effect**

# Ambiguity Resolution - Narrow and Wide Lanes



apparent signal transmission times:

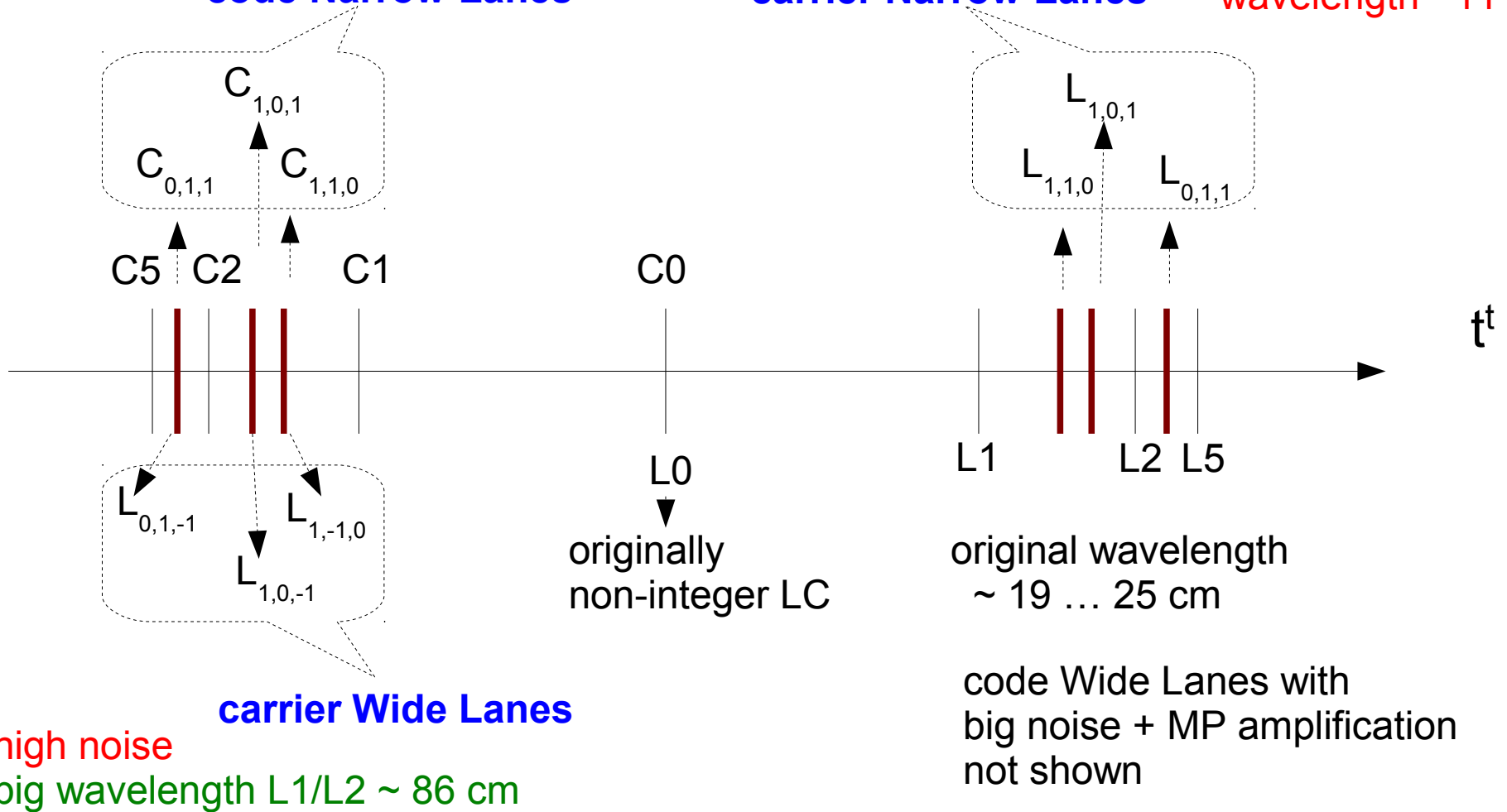
low noise

code Narrow Lanes

carrier Narrow Lanes

low noise

wavelength ~ 11 cm



# Ambiguity Resolution



- ambiguity resolution
  - **requires consistent** satellite phase and code **biases**
  - **increasing complexity** with variety of signals and GNSS
- RTCM-SSR biases support ambiguity resolution condition, furthermore
  - flexible, serves different approaches and strategies
- indication of **partial services** required in RTCM-SSR
- services may be based on
  - ionospheric free linear combination
  - on float/fixed ambiguities on reference stations
  - particular characteristic/consistency of RTCM-SSR

# Ambiguity Resolution



- basic **content of RTCM-SSR** satellite **phase signals** and **properties to indicate partial services**
  - per GNSS
    - satellite **bias-free ionospheric observable** indicator (dispersive bias consistency indicator)
    - satellite **bias free code/phase observable** indicator (Melbourne-Wübbena - MW consistency indicator)
  - per satellite
    - **yaw** angle and yaw rate
  - per GNSS signal and tracking mode
    - satellite **bias free phase with integer nature** indicators (signal integer indicator, signal wide lane integer indicator and signal discontinuity counter)
    - **phase bias**



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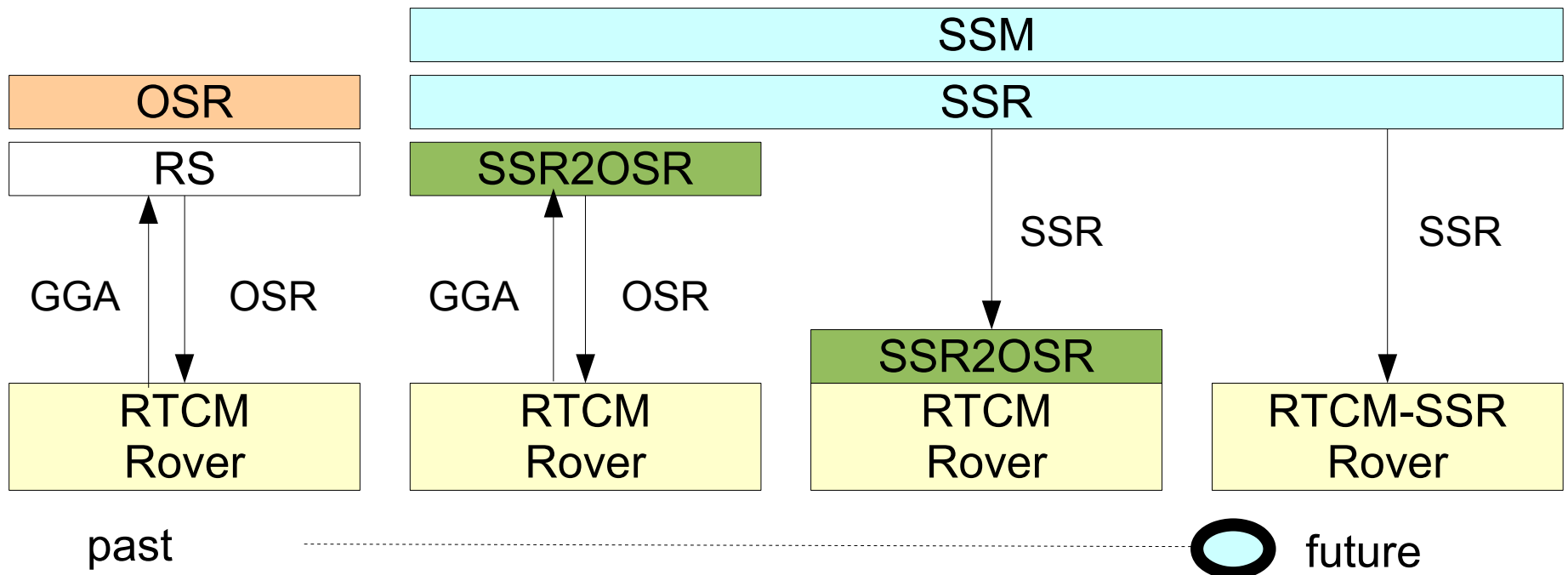
# RTCM SSR Working Group - Status



- Stage 1 DF-RT-PPP  
**standardized** since Mai 2011: GPS GLONASS  
**proposed**/interoperability testing: Galileo QZSS SBAS BDS
  
- Stage 2 SF-RT-PPP/RT-PPP  
**proposed**/interoperability testing: satellite phase bias messages  
vertical TEC (VTEC) message  
(spherical harmonics)
  
- Stage 3 RTK-PPP  
**initial concepts**  
**under consideration** slant TEC (STEC) messages  
troposphere
  
- availability of new proposed messages depends on some technical issues, interoperability tests and on progress in RTCM
- need for an additional Stage 4 (“first define contents”)
  
- **Stage 4 Compression**  
compression of messages/reduce of bandwidth



# SSR Application for GNSS Positioning



SSM State Space Monitoring  
 OSR observation space representation  
 SSR state space representation  
 RS reference station  
 GGA NMEA position message

· SSM/SSR concept operationally applied with Geo++ GNSMART



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# Summary/Outlook

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- SSR standardization is challenging
- RTCM-SSR messages shall
  - be self-contained, flexible and non restricting
  - serve scalable applications and accuracy requirements
- ambiguity resolution for PPP supported by proposed satellite phase biases support ambiguity resolution
- SSR standardization requires time; next steps are
  - interoperability testing of proposed RTCM-SSR messages
  - start on Stage 3 RTCM-SSR development
- SSR can replace OSR techniques for all types of GNSS positioning applications with better performance and less costs
- need for demonstration of SSR performance to convince markets

# Standardized RTCM SSR Messages



- Stage 1 for GPS and GLONASS

<b>Message Type</b>	<b>Message Name</b>
1057	SSR <b>GPS Orbit</b> Correction
1058	SSR <b>GPS Clock</b> Correction
1059	SSR <b>GPS Code Bias</b>
1060	SSR GPS Combined Orbit and Clock Corrections
1061	SSR GPS URA
1062	SSR GPS High Rate Clock Correction
1063	SSR <b>GLONASS Orbit</b> Correction
1064	SSR <b>GLONASS Clock</b> Correction
1065	SSR <b>GLONASS Code Bias</b>
1066	SSR GLONASS Combined Orbit and Clock Correction
1067	SSR GLONASS URA
1068	SSR GLONASS High Rate Clock Correction

# Proposed RTCM SSR Messages (May 2012)



- Stage 1 RTCM SSR Galileo QZSS

Message Type	Message Name
1240	SSR <b>Galileo Orbit</b> Correction
1241	SSR <b>Galileo Clock</b> Correction
1242	SSR <b>Galileo Code Bias</b>
1243	SSR <b>Galileo</b> Combined Orbit and Clock Corrections
1244	SSR <b>Galileo</b> URA
1245	SSR <b>Galileo</b> High Rate Clock Correction
1246	SSR <b>QZSS Orbit</b> Correction
1247	SSR <b>QZSS Clock</b> Correction
1248	SSR <b>QZSS Code Bias</b>
1249	SSR <b>QZSS</b> Combined Orbit and Clock Correction
1250	SSR <b>QZSS</b> URA
1251	SSR <b>QZSS</b> High Rate Clock Correction

# Proposed RTCM SSR Messages (May 2012)



- Stage 1 RTCM SSR SBAS BDS

Message Type	Message Name
1252	SSR <b>SBAS Orbit</b> Correction
1253	SSR <b>SBAS Clock</b> Correction
1254	SSR <b>SBAS Code Bias</b>
1255	SSR <b>SBAS</b> Combined Orbit and Clock Corrections
1256	SSR <b>SBAS</b> URA
1257	SSR <b>SBAS</b> High Rate Clock Correction
1258	SSR <b>BDS Orbit</b> Correction
1259	SSR <b>BDS Clock</b> Correction
1260	SSR <b>BDS Code Bias</b>
1261	SSR <b>BDS</b> Combined Orbit and Clock Correction
1262	SSR <b>BDS</b> URA
1263	SSR <b>BDS</b> High Rate Clock Correction

# Proposed RTCM SSR Messages (May 2012)



- Stage 2 RTCM SSR Satellite Phase Bias

Message Type	Message Name
1265	SSR Satellite <b>GPS</b> Phase Bias
1266	SSR Satellite <b>GLONASS</b> Phase Bias
1267	SSR Satellite <b>Galileo</b> Phase Bias
1268	SSR Satellite <b>QZSS</b> Phase Bias
1269	SSR Satellite <b>SBAS</b> Phase Bias
1270	SSR Satellite <b>BDS</b> Phase Bias

# Proposed RTCM SSR Messages (May 2012)



- Stage 2 RTCM SSR VTEC

<b>Message Type</b>	<b>Message Name</b>
1264	SSR Ionosphere Spherical Harmonics